# **Automatic Design of Missions to Small Bodies**

Candidate Selection and Feasibility Studies



Javier Roa, Alan B. Chamberlin, Ryan S. Park, Anastassios E. Petropoulos,

Paul W. Chodas, Damon Landau, Davide Farnocchia

Jet Propulsion Laboratory, California Institute of Technology

AIAA/AAS Spaceflight Mechanics Conference, January 8-12, 2018

## **Orbit Determination**

The AUTO System



COLLECT OBSERVATIONS NEW ORBIT SOLUTION

STORE IN SMALL-BODY DATABASE

**END USER** 











**HORIZONS** system

## **Pre-computed Solutions**

Filter for rapid candidate selection:

Physical + orbital + mission-design

parameters

### Interactive Interface

Single-body analysis, access to latest orbit solutions.

Impulsive missions + Low-thrust ∆V estimates

## Mission Design System

## **Operation Modes**



### Query Mode: all bodies

- Pre-compute impulsive, optimal mission opportunities.
- Phase-free low-thrust ΔV estimate.
- Stored in the Small-Body Database for fast lookup, updated periodically.
- Combined query: orbital + physical + mission-design parameters.

### Framework for rapid candidate selection

### Detailed Mode: each body

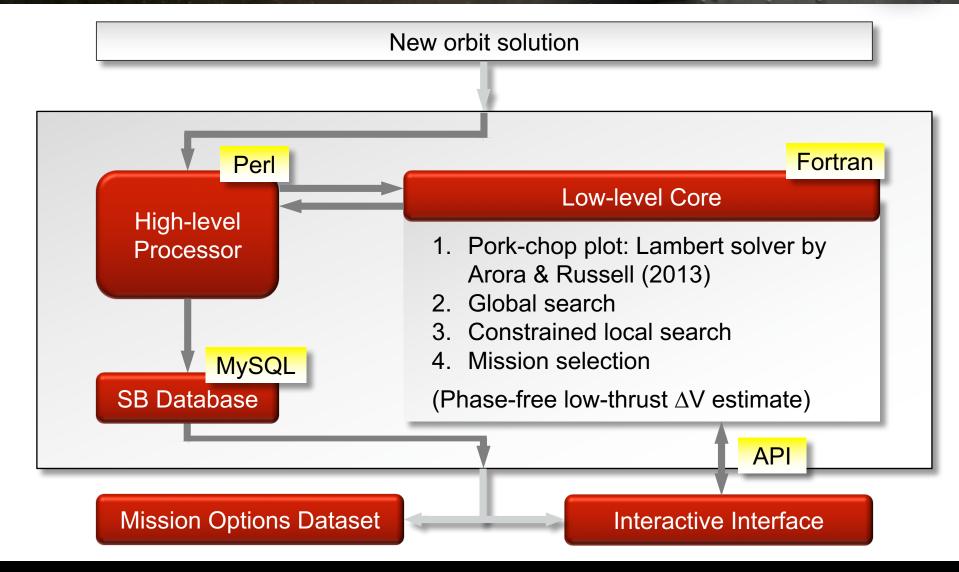
- Interactive interface: More in-depth analysis of each candidate body.
- Preliminary mission selection.
- Access to latest orbit solution + newly discovered bodies.

## **Preliminary analysis of feasible solutions**

# Mission Design System

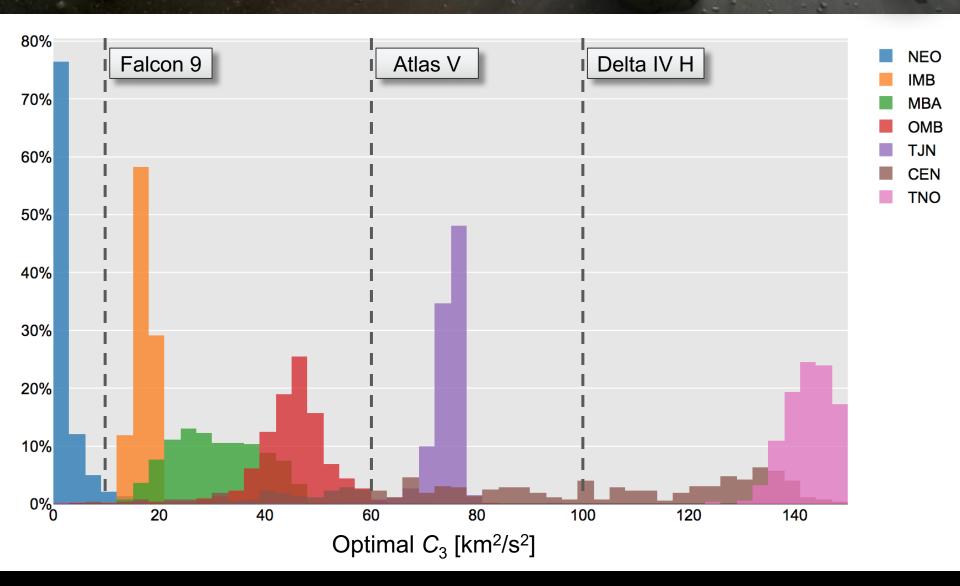


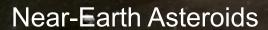




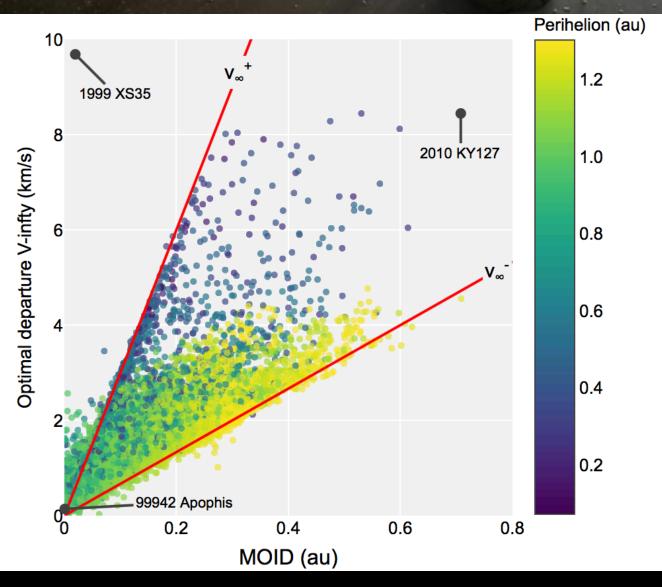


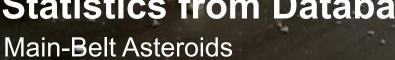




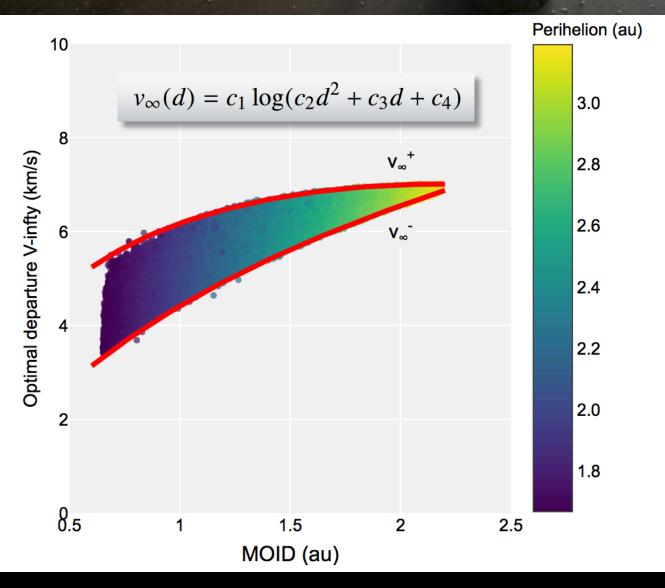


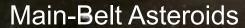








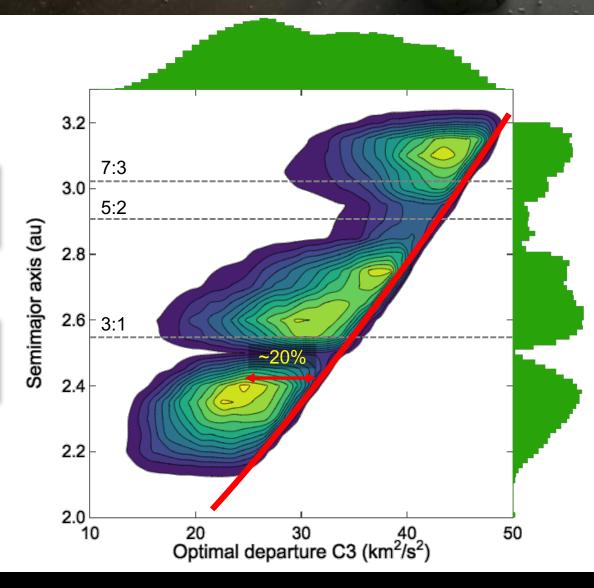


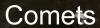




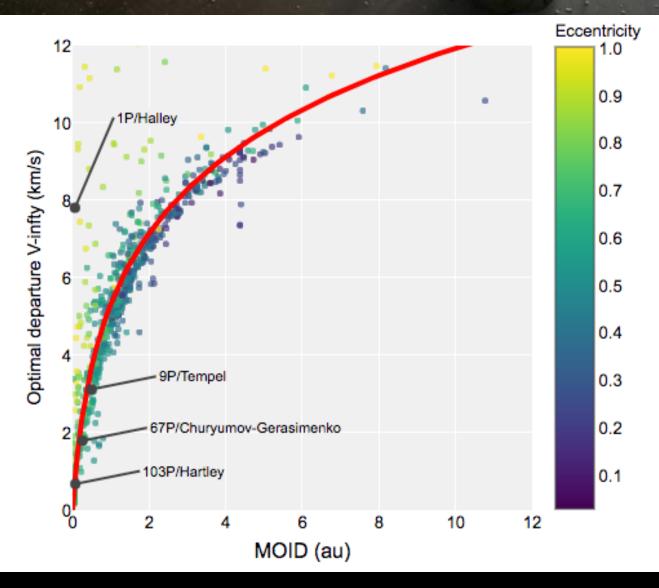
Kirkwood Gaps

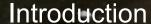
Hohmann Approx.















### **Overview**

Welcome to the JPL/SSD Small-Body Mission-Design System. The system has been designed to enable rapid mission design to all known small bodies (asteroids and comets) [1]. There are two operation modes available to the user:

- Candidate selection: the system includes a database of pre-computed optimal impulsive missions to all known small bodies. The database is kept
  current automatically with the JPL Solar System Dynamics Group (JPL/SSDG) small-body catalog, and it is updated periodically. Using the Small-Body
  Search Engine, the user can filter the database to find lists of small bodies that have certain physical or orbital properties, and that can be reached
  under certain mission-design constraints. This operation mode is useful for identifying potential candidates for future missions. In addition, the
  database includes a phase-free low-thrust estimate of the ΔV required to reach the orbit of the small body, assuming constant thrust acceleration [2].
- Mission opportunities to a specific small body: the second operation mode allows users to find mission opportunities to a specific small body. We
  provide an interactive web interface to analyze mission options to each and every small body in the database. Use this mode if you are interested in
  designing a mission to a specific asteroid or comet.

Each operation mode is explained in more detail in the following lines.

### Static Information



10	I /een	Small Bad	Mission Design	Suntam
JF	LOOD	Siliali-Dou	y Mission-Design	System

Introduction

Design Interface

Tutorial

FAQ

Small-Body Search Engine

## 99942 Apophis (2004 MN4)

The interactive interface of the JPL/SSD Small-Body Mission-Design System includes three sections:

- Mission Options: contains an interactive data table presenting different mission options to the specified small body. Initially, the table is populated with a set of pre-computed trajectories.
   Details on the selection process and the back-end algorithms can be found in the Introduction.
   Missions selected using the interactive tools will appear in the table, with increasing "Id" numbers.
- Mission Selection: use the interactive contour plot to select new missions by clicking on the map, or to explore the details of the solutions already on the table.
- Launch Vehicle Selection: the plot shows the capabilities of different launch vehicles, considering both flyby and rendezvous missions. Click on the plot to add missions to the data table.

A tutorial is available for first-time users with detailed information about each component of the interface. This tool can be used in combination with the Small-Body Search engine, designed to find candidate targets.

#### **Orbit Data**

Search:

 Classification:
 Aten

 SPK-ID:
 2099942

 Orbit Id:
 193

 Condition code:
 0

 Data arc span (days):
 3635

#### **Low Thrust**

Estimate of the  $\Delta V$  required to reach the target orbit, disregarding the phasing within the orbits and the transfer time and assuming constant acceleration.

ΔV estimate: 4.79 km/s

## Table of Selected Missions

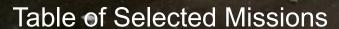


#### **Mission Options:**

The following table lists relevant mission options. Each mission is assigned a unique "Id" to distinguish it from the rest. Initially, it contains a set of preselected solutions that capture the optimal launch opportunities (minimizing the departure C3). The table presents additional mission options including minimum time of flight and minimum arrival V-infinity. Switch to **Mass mode** to see launch-vehicle capabilities. Order by decreasing "Id" (default) to see the new records on top.

Use the interactive tools Mission Selection and Launch Vehicle Selection to add missions to the table by simply clicking on the plots. Selected trajectories can be **plotted** in the ICRF system, using the Ecliptic at J2000 as the reference plane.

Download Select all		Deselect al	ect all Plot trajectories		Delete selected		ΔV mode Mass mode			Show 10 v entries				
ld <b>▼</b>	Departure (cal)	e date (MJD) 🌲	Arrival (cal)	date (MJD) 🌲	TOF (days)	C3 (km²/s²)	V∞ dep. (km/s)	V <sub>~</sub> arr. (km/s)	Total ΔV (km/s)	Phase angle (deg)	Dist. Earth (au)	Pump angle (deg)	SEP angle (deg)	DLA (deg)
863	2028-08-25	62008	2029-04-12	62238	230	0.0	0.1	5.9	6.0	24.7	0.01	82.6	156.6	41.3
862	2028-07-31	61983	2029-04-12	62238	255	0.0	0.1	5.8	6.0	24.7	0.01	82.5	156.6	43.0
861	2028-12-18	62123	2029-04-12	62238	115	0.0	0.1	6.0	6.2	24.1	0.01	82.4	156.6	-39.9
860	2029-01-17	62153	2029-04-12	62238	85	0.0	0.2	6.1	6.2	24.3	0.01	82.2	156.6	-38.8
859	2028-11-23	62098	2029-04-12	62238	140	0.0	0.2	6.0	6.1	23.8	0.01	82.5	156.6	-42.3
858	2028-01-18	61788	2029-04-12	62238	450	0.1	0.2	5.8	6.0	24.5	0.01	82.8	156.6	7.7
857	2028-02-17	61818	2029-04-12	62238	420	0.1	0.2	5.9	6.1	24.2	0.01	83.2	156.6	-1.6
856	2028-05-27	61918	2029-04-12	62238	320	0.1	0.3	5.6	5.9	25.0	0.01	82.0	156.6	38.2
855	2020-01-20	58868	2021-04-19	59323	455	0.1	0.3	6.1	6.4	24.6	0.16	81.3	89.6	-37.1
854	2020-06-23	59023	2021-04-19	59323	300	0.1	0.3	5.2	5.5	28.8	0.16	77.8	89.6	31.5
Showing 1 to 10 of 863 entries									Previous	1 2	3 4	5	87	Next





#### **Mission Options:**

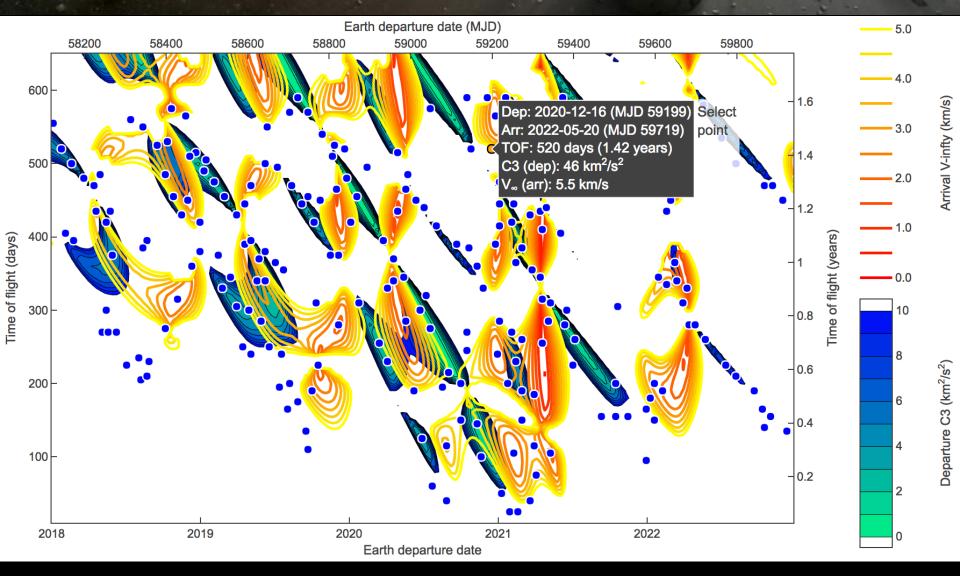
The following table lists relevant mission options. Each mission is assigned a unique "Id" to distinguish it from the rest. Initially, it contains a set of preselected solutions that capture the optimal launch opportunities (minimizing the departure C3). The table presents additional mission options including minimum time of flight and minimum arrival V-infinity. Switch to **Mass mode** to see launch-vehicle capabilities. Order by decreasing "Id" (default) to see the new records on top.

Use the interactive tools Mission Selection and Launch Vehicle Selection to add missions to the table by simply clicking on the plots. Selected trajectories can be **plotted** in the ICRF system, using the Ecliptic at J2000 as the reference plane.

Download Select all		Deselect all	Plot traj	ectories	Delete se	lected		ΔV mod	de Mass	s mode		Show 10	entries	
ld .	Atlas V (531) (kg)		Atlas V (551) (kg)		Falcon 9 (kg)		Falcon Heavy (kg)		Delta IV-H (kg)		SLS 1B (kg)		SLS 2 (kg)	
ld ₩	Flyby 🍦	Rdzvs 👙	Flyby 🍦	Rdzvs 🝦	Flyby 👙	Rdzvs 👙	Flyby 🖕	Rdzvs 🍦	Flyby 🝦	Rdzvs 🝦	Flyby 🍦	Rdzvs 👙	Flyby 🍦	Rdzvs 🍦
863	4935	760	6100	940	3305	510	12420	1915	10180	1570	22735	3505	52315	8075
862	4935	770	6100	955	3305	515	12420	1945	10180	1595	22735	3560	52315	8200
861	4935	725	6100	895	3305	485	12420	1820	10180	1490	22735	3335	52315	7680
860	4935	710	6100	875	3305	475	12420	1785	10180	1460	22730	3270	52315	7525
859	4935	735	6100	910	3305	490	12420	1855	10180	1520	22730	3395	52315	7810
858	4935	785	6095	970	3300	525	12415	1975	10175	1620	22720	3615	52295	8325
857	4930	750	6095	925	3300	500	12415	1890	10170	1545	22715	3455	52290	7960
856	4930	820	6095	1015	3300	550	12410	2075	10170	1700	22710	3795	52280	8740
855	4930	705	6095	870	3300	470	12410	1780	10170	1455	22710	3255	52280	7500
854	4930	930	6095	1150	3300	620	12410	2340	10170	1920	22705	4285	52275	9875
Showir	ng 1 to 10 c	of 863 entries	6						Previous	1 2	3	4 5	87	Next

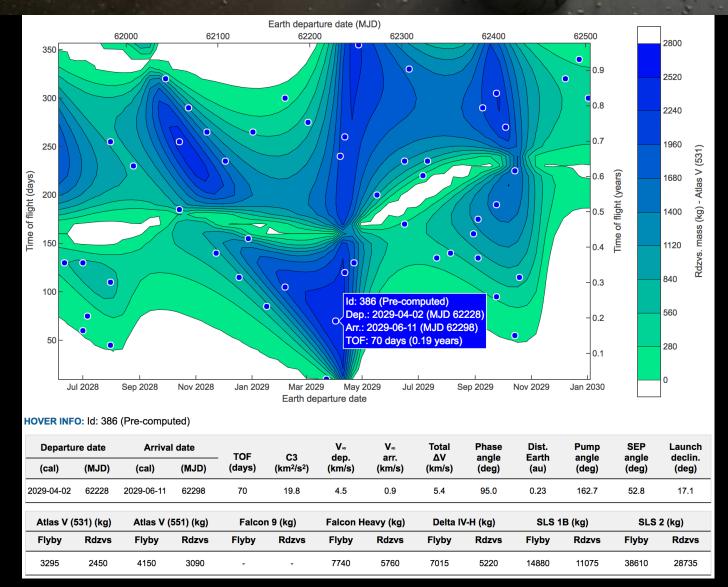
Interactive Pork-Chop Plot

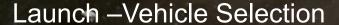




## Interactive Pork-Chop Plot



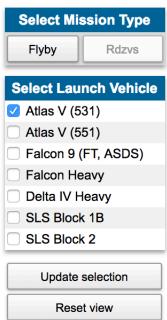


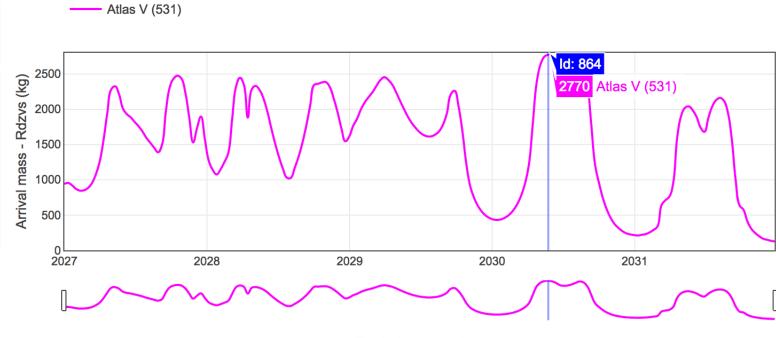




#### Launch-Vehicle Selection:

The figure displays the maximum mass of the spacecraft that will reach the target body when launched on a certain date. Use the control panels to select the mission type (flyby or rendezvous), and to update the list of launch vehicles. Click on the plot to add missions to the Mission Options table. Zoom in using the slider under the figure or by clicking and dragging on the chart.





Earth departure date

## Conclusions



### Statistical results

Analytic estimate of the limits on the departure V-infinity.

#### Candidate Selection

- Find list of candidate targets in seconds.
- Combined with physical + orbital parameters.
- Database of pre-computed solutions, publicly available.
- DB is kept current automatically.

## **Preliminary Design**

- Use web interface to select dates and launch vehicle.
- Save data for post-processing.
- Fast access to latest ephemeris.

## Thank you!



javier.roa@jpl.nasa.gov